



Introduction

We propose a new approach to achieve instance-level domain adaptation results without any detection subnet integration

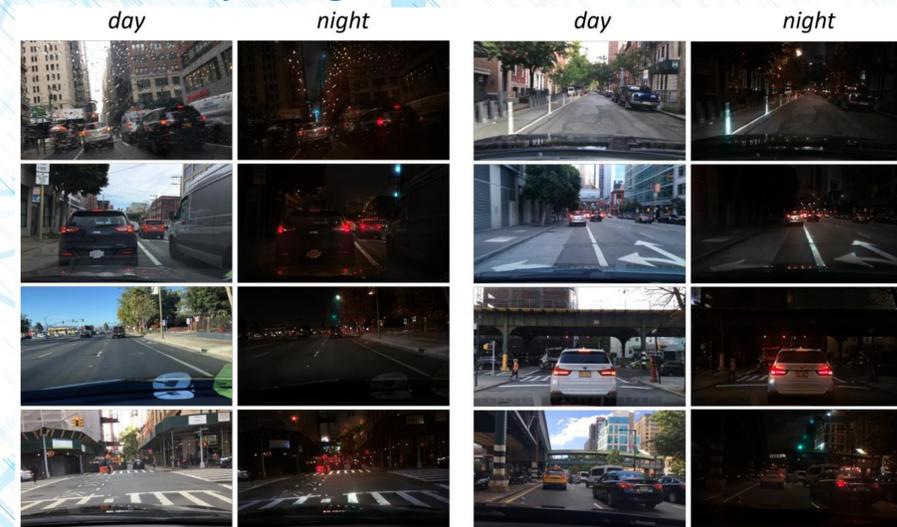
Our contributions consist of following:

- **Masking**
- **Cycle-Object Edge Consistency Loss**

Github repository link is available in the QR code.

Results

BDD100k day to night



SOTA Comparison



Qualitative & quantitative (FID score) comparison	GAN model	annotation?	GTA	BDD100k
	MUNIT [16]	No	1.066	2.461
	NICE-GAN [15]	No	2.466	1.913
	AugGAN [5]	Yes	0.825	0.332
	Multimodal AugGAN [6]	Yes	1.023	0.496
	CyEDA (This work)	No	0.737	0.297

Methodology

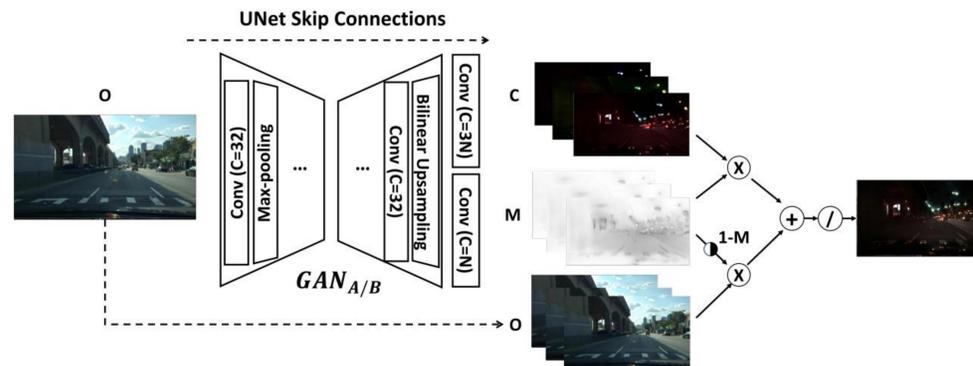
Mask UNet

Model learns to **make color changes to every pixel of original image** instead of generating whole image from hidden embedding.

We modify the last layer of UNet into two separate blocks:

- a convolution layer that yields $3N$ channels of output followed by \tanh activation layer (**predicted color changes, C**)
- a convolution layer that yields N channels of output followed by sigmoid activation layer (**predicted degree of color changes / mask, M**)

Translated image is computed by summing the weighted mask of color changes and the inverted weighted mask of the original image and normalized by number of mask N

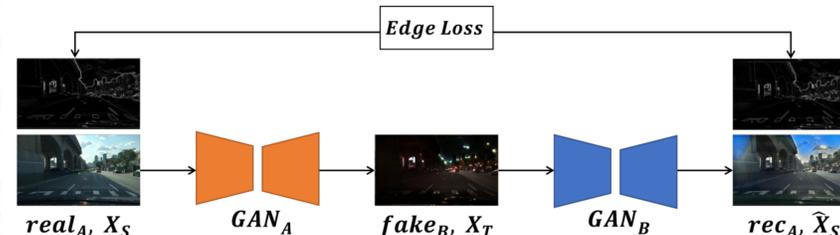


Cycle-Object Edge Consistency Loss

CycleGAN learns to hide information in the network to satisfy $L1$ cycle consistency requirement [1].

We argue that the cycle consistency loss should only enforce the preservation of objects in the images instead of every pixel details.

We **enforce $L1$ consistency between edge of real and reconstructed images** instead of the image itself.



Ablation Study

Mask UNet contributes on **maintaining colour contrast** of translated image as can be seen in Fig.(c) and edge loss **removes unnecessary details** as shown in Fig.(d).



Qualitative and quantitative results of ablation study to show contributions of Mask Unet and Cycle-Object Edge Consistency Loss

Experiment Settings	FID
No mask + L1 (CycleGAN + UNet)	0.551
No mask + Edge	0.579
Mask + L1	0.389
Mask + Edge (CyEDA)	0.297

Domain Adaptation

YOLOv5s model is used to train with BDD100k real night images with and without translated day-to-night images.

Training Dataset (BDD100k)	mAP (whole)	AP (car)
det-train-night	0.444	0.627
+ det-val-day day-to-night	0.465	0.644

Conclusion

This paper introduced an approach to retain instance-level detail when translating images to a target domain by

- generating masks from UNet and performing color fine-tuning on original images according to the masks
- using cycle-object edge consistency loss to remove unnecessary details and provide extra capacity for model to perform more realistic image-translation

Reference

1. Casey Chu, Andrey Zhmoginov, and Mark Sandler, "Cyclegan, a master of steganography," arXiv preprint arXiv:1712.02950, 2017.